Robust and Reliable Control in Decentralized Singularly-perturbed Systems

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Abstract

Robust control investigation and reliable control investigation are performed in his research for decentralized singularly-perturbed systems [1]. Due to the systems are controlled by using reduced-order control scheme, robustness of the system should be necessarily concerned. A procedure of a robust control test will be developed to find the robustness bound of the systems. A reliability goal for a decentralized system is the stabilization of the plant by a controller in each control channel, such that the system can tolerate control channel failures [2]. The results of the research shows the system that has a certain structure with certain conditions will be a reliable control system.

Key words: Control System; Reliability; Singularly-Perturbed System

分散式奇異擾動系統之強健及可靠性控制

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摘要

在這篇研究中,分散式奇異擾動系統之強健及可靠性控制被加以研究

和討論。因為此系統由減階控制器控制,系統的強健性必須被加以考

量。一種強健控制的測試方法亦被發展出來,系統之強健界線亦可由

此法找出。可靠性在於分散式奇異擾動系統是指在每個控制端的控制

器可穩定受控系統,且使得受控系統可忍受任意控制端的失效。這篇

研究的結果顯現出只要符合特一架構的控制系統加上一定的條件,此

系統將會是一個可靠性的控制系統。

關鍵字: 控制系統;可靠度;奇異擾動系統